

## MPD Thruster Technology Workshop

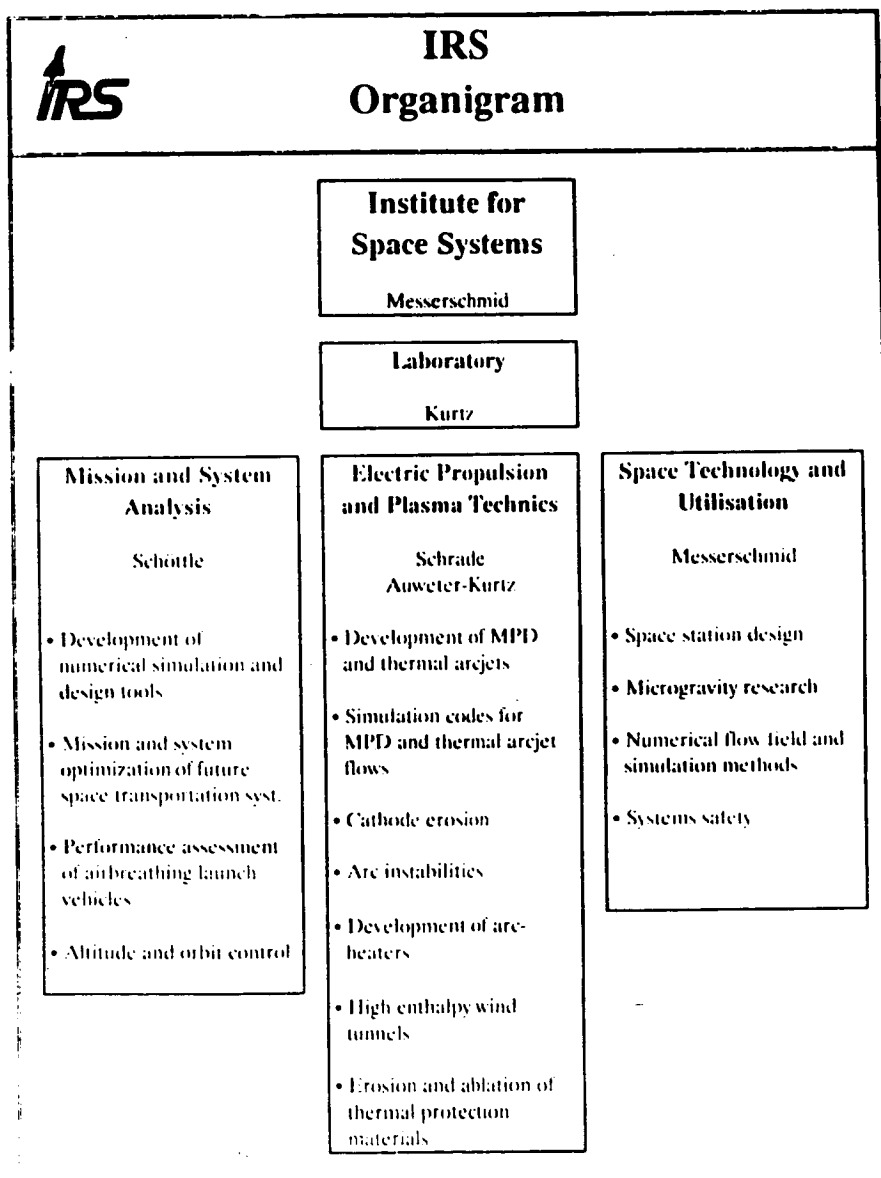
NASA H.Q., Washington D.C.

16 May 1991

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## IRS Presentation

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# Electric Propulsion and Plasma Wind Tunnel

## Activities at the IRS

May 1991

Activity / Thruster	MPD (Selffield)	Arcjet			Reentry (Material-Tests)		Missions. Trajectories
Power Level	100 kW-1 MW	1 kW	< 20 kW	< 100 kW	$h_0 < 10^8$ J/kg		
Isp [km/s]	10 - 20	5 - 6	< 10	10 - 15			
Thrust [N]	5 - 20	0.1	> 1	> 10			
Propellant	Ar, N <sub>2</sub> , H <sub>2</sub> , NH <sub>3</sub>	NH <sub>3</sub> , H <sub>2</sub> , N <sub>2</sub> -H <sub>2</sub>	N <sub>2</sub> -H <sub>2</sub> , H <sub>2</sub>	NH <sub>3</sub> , H <sub>2</sub>			
Theories	Flowfield Stability Arc-Attachment Erosion	Constrictor Flow Heat Transport					Traject. - Optimizat.
Diagnostics	Emission Spectroscopy, el. Probes, Fabry-Perot Interferometry, Mechan. Probes, Mass Spectroscopy, Optical Temperature Measurement						
Status	Water Cooled Laboratory Devices	Radiation Cooled Lab. Model	Water Cooled Devices	Water Cooled Devices	PWK1 - IRS Operat. since 1987	PWK2 - IRS Operative	in Work
Contractors	USAF DFG BMFT	DARA		NASA (IST)	ESA / CNES, AMD-BA, AS, SEP, DO, MBB, MAN, DLR	DARA SFB ESA, FGE	



## IRS Facilities

### High DC Power Supply:

Power:  $\leq 6$  MW  
Current:  $\leq 48$  kA  
Ripple:  $\leq 1\%$

### Vacuum System:

#### Four Stage Pump System:

- 1) 3 MTP 50,000 m<sup>3</sup>/h roots pumps  
1 Alcatel 120,000 m<sup>3</sup>/h roots pump
- 2) 1 MTP 50,000 m<sup>3</sup>/h roots pump
- 3) 1 multiple slide valve type pump RV 500
- 4) Rotary vane pump BA 600

Total suction power:  $> 200,000$  m<sup>3</sup>/h at 10 Pa  
Tank pressure can be set

### Vacuum tanks:

8 tanks connected to vacuum system

6 for plasma accelerator development  
2 plasma wind tunnels

2 independent test stands for smaller thrusters or basic experiments



## **History of MPD Activities at IRS**

<b>1976</b>	<b>Begin of Building-Up of IRS Propulsion Laboratory</b>
<b>1982-1991</b>	<b>Cooperation Grants "Basic Processes of Plasma Propulsion" from AFOSR (analytical and numerical).</b>
<b>1982-1991</b>	<b>Cooperation Grants with interruptions "MPD Thruster Development" from AFRPL, AFOSR. 1987-1988 financed by the SDIO over ONR (experimental and numerical).</b>
<b>1989-1991</b>	<b>"MPD Thruster Instabilities", contract by the German Research Organisation DFG (theoretical studies).</b>
<b>1990-1993</b>	<b>"Plasma Instabilities in MPD Thrusters", contract by the German Ministry of Research BMFT (numerical and experimental; together with MAN).</b>



## **History of Thermal Arcjet Activities at IRS**

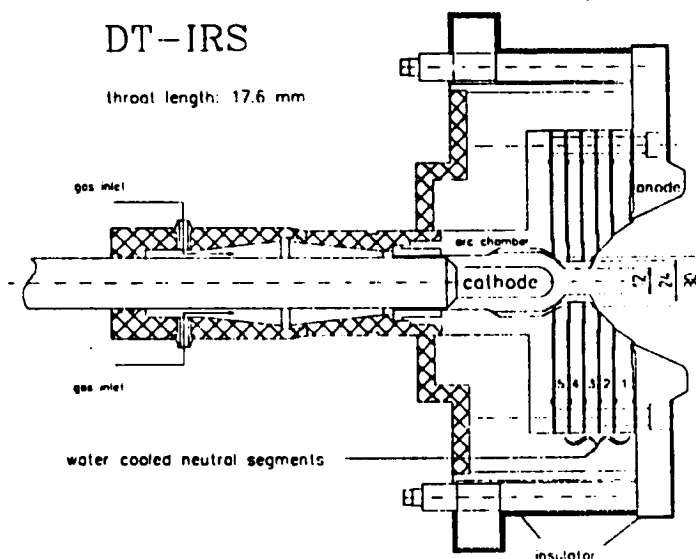
- 1986-1990 "Arcjet Flow Analysis", contract by ESA/ESTEC (analytical and numerical).**
- 1987-1990 "1 N Arcjet", sub-contract by ESA/ESTEC (experimental), main-contractor BPD, Italy.**
- 1989-1991 "High Power Arcjet", Cooperation Grant by NASA (IST) (experimental and numerical studies).**
- 1990-1993 "A 1 kW Hydrazine Arcjet", contract by the German Aerospace Agency DARA (together with MBB).**



## Nozzle Type Thruster DT-IRS

DT-IRS

throat length: 17.6 mm



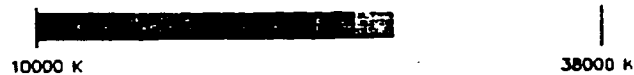
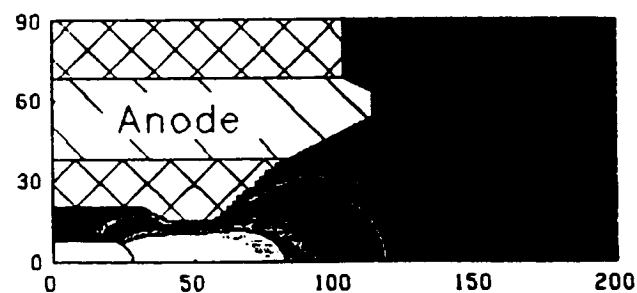
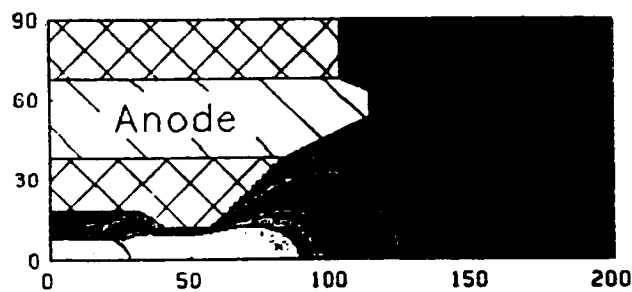
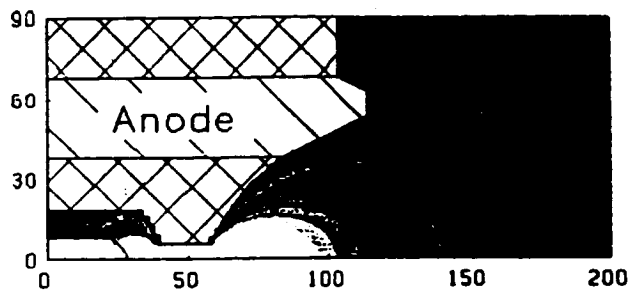
Configuration of the DT-Thrusters with different throat diameters

Maximum values reached with the DT2-Thruster with argon as propellant:

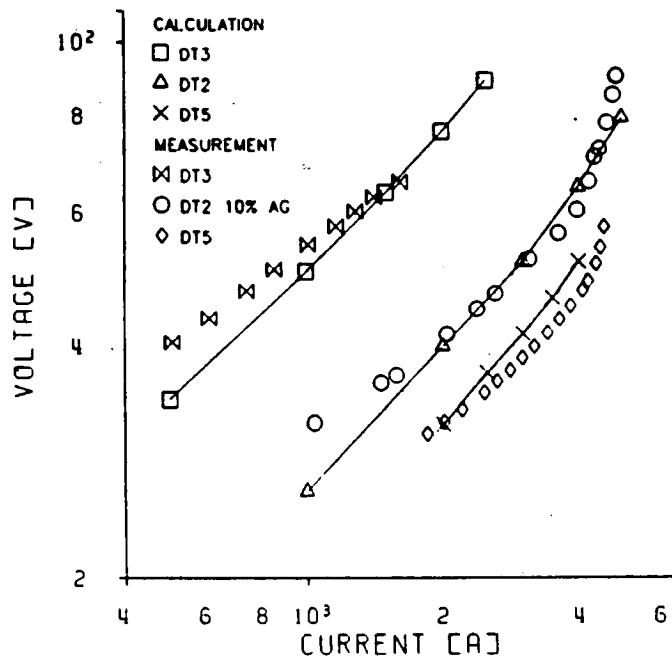
electrical power:  $P_{el} \leq 800 \text{ kW}$

specific impulse:  $I_{sp} \leq 1500 \text{ s}$

thrust efficiency:  $\eta_f \leq 25\%$



Electron temperature distribution for three different throat geometries at 2 kA current and a mass flow of 0.8 g/s.



Calculated and measured discharge voltage.





## Nozzle Type MPD Thrusters .

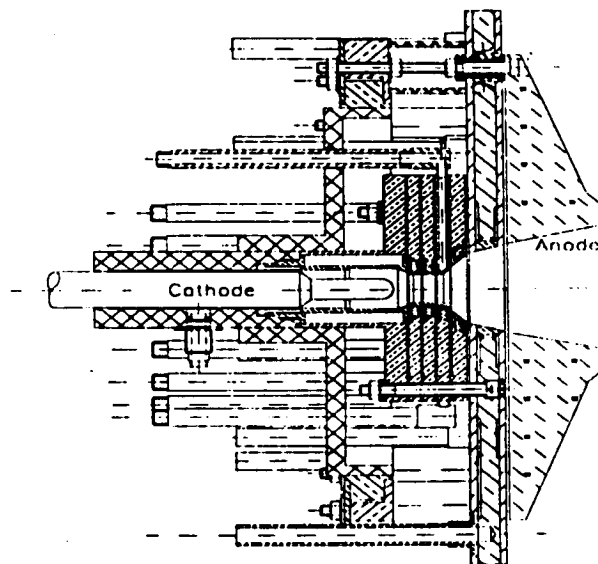
- 1.) Specific impulse limited to 1500 s because of low  $\frac{I^2}{\dot{m}}$  - values.  
( Onset - Phenomenon )
- 2.) Efficiency : not more than 30% achieved with experiments.  
Expectation with higher massflow rates and higher power:  
above 30% .
- 3.) High power limitations: Heat load of nozzle throat.
- 4.) Propellant: no significant difference in  $\eta$  and  $c_e$  with Ar, N<sub>2</sub>, H<sub>2</sub>,  
lower  $\frac{I^2}{\dot{m}}$  with H<sub>2</sub> and N<sub>2</sub> .
- 5.) High power limits:  
vacuum system ( high power  $\Rightarrow$  high mass flow rates )  
( Influence of ambient pressure not so important with  
selffield MPD's )

### Research plans: Geometry optimization:

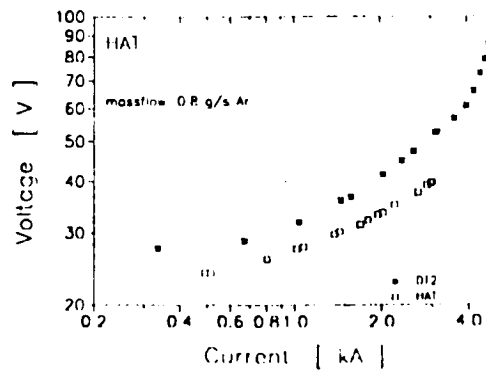
- Transition from nozzle to conical (flared) configurations.
- Radiation cooled anode.



## Hot Anode Thruster ( HAT )



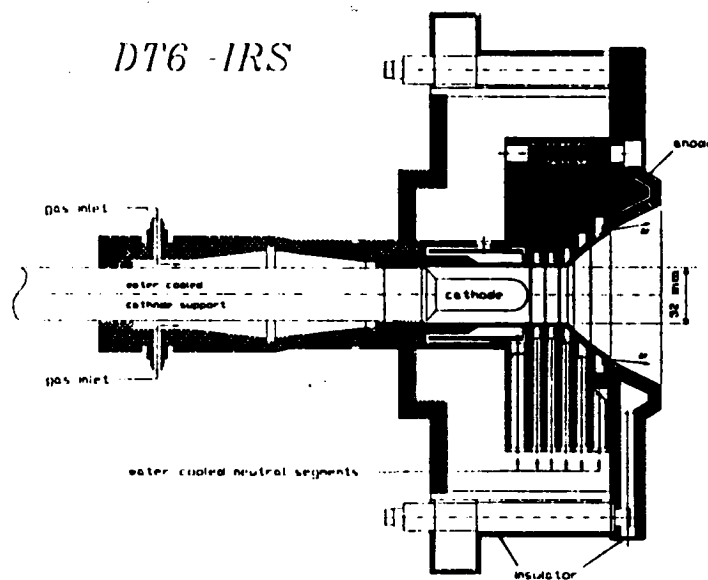
Configuration of the HAT-Thruster with radiation cooled anode



Voltage vs. current dependence for the HAT in comparison with the DT2-Thruster



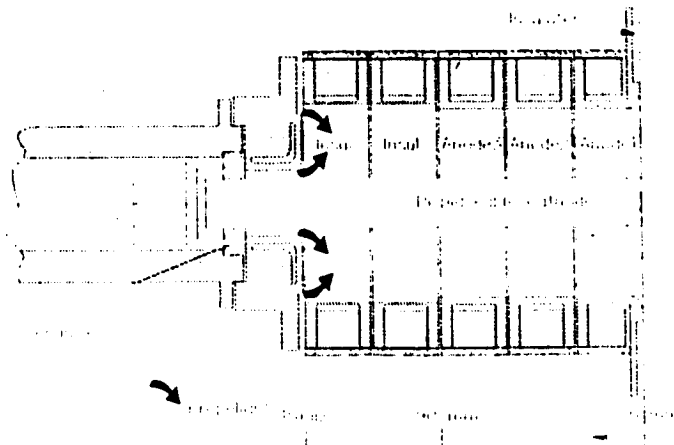
## DT6-Thruster



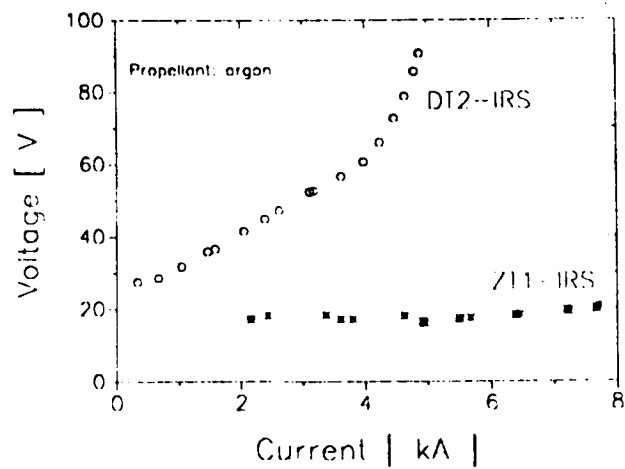
Configuration of the DT6-Thruster without throat constriction  
( in construction )



## ZT1-Thruster



Configuration of the cylindrical ZT1-Thruster

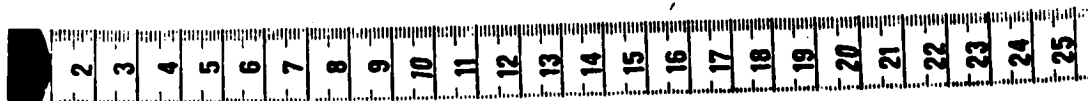
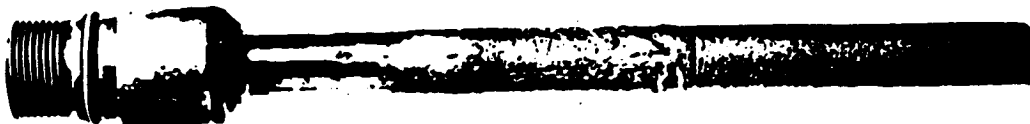


Voltage vs. current dependence for the ZT1- respectively DT2-Thruster with argon as propellant

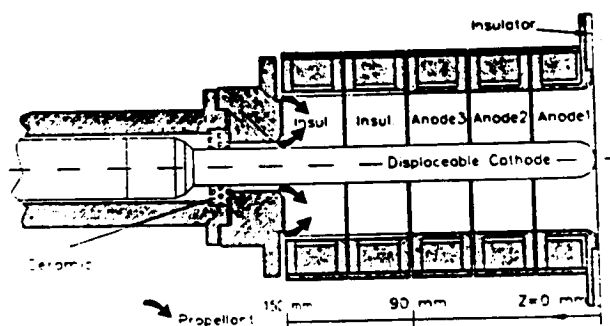


## Cylindrical MPD thruster

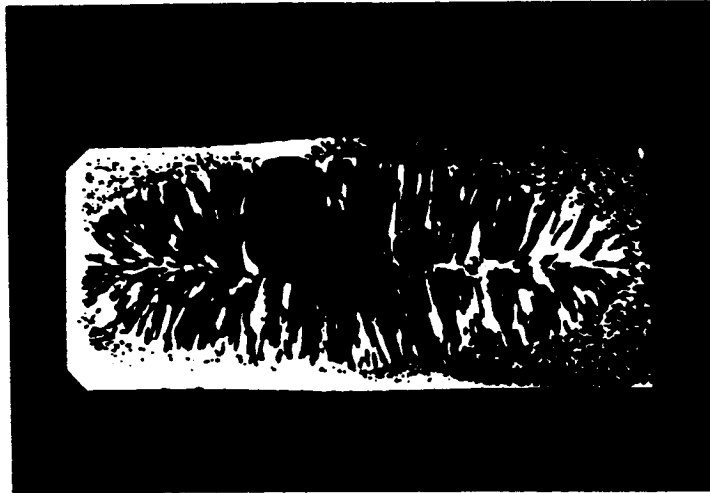
- 1.) Higher onset (  $\frac{I^2}{m}$  ) than with nozzle type thrusters  
⇒ higher specific impulse possible.
- 2.) Efficiency with continuous thruster not yet measured.  
( Thrust balance in construction. )
- 3.) Lower voltage levels than with nozzle type thrusters.
- 4.) High current issues:
  - a) heat loads to anode ( ~ I )
  - b) heat loads to cathode: can be solved by cathode geometrical configuration.
- 5.) High power limits:  
vacuum system ( high power ⇒ high massflow rates )  
( Not so important with selffield MPD )



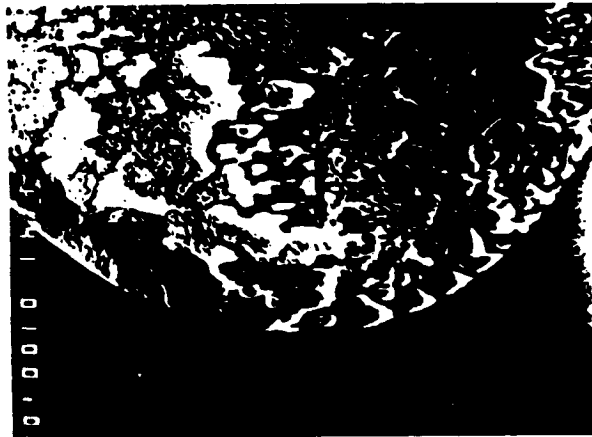
DAMAGED CATHODE OF THRUSTER ZT1



SCHEME OF THRUSTER ZT1



TYPICAL STRUCTURE OF AREA I ( MELTED ZONE )



DETAIL OF THE VOID

ORIGINAL PAGE IS  
OF POOR QUALITY



## Comparison

continuous MPD ↔ quasi-steady MPD

Biggest problem: different cathode modes:

thermionic ↔ cold

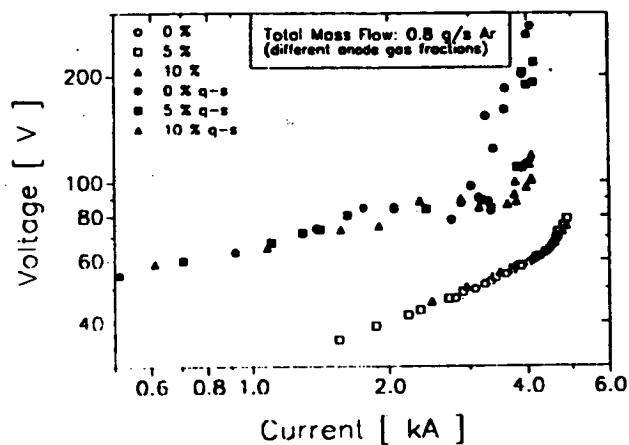
- different arc attachments
- different voltages
- different current distributions



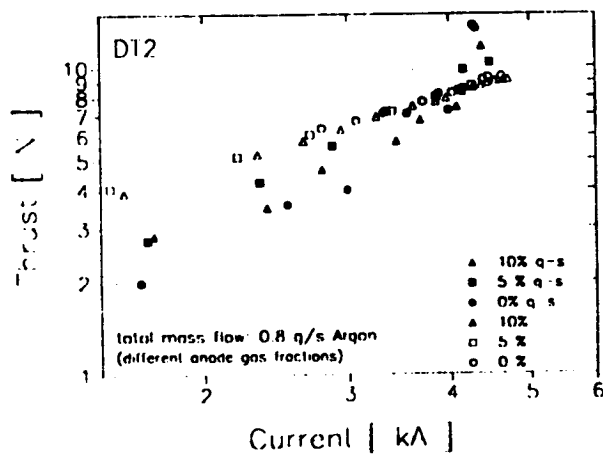


## Comparison

continuous MPD ↔ quasi-steady MPD



Comparison of the voltage vs. current dependence for the continuous DT2-Thruster ( open signs ) and the quasi-steady MPD-Thruster ( Closed signs )



Thrust vs. current curves for both thrusters



## **MPD-Thrusters**

### **1.) Nozzle Type MPD-Thrusters ( DT-IRS serie )**

- Geometrical optimisation of the nozzle  
( experimental and numerical )
- Investigation of the plasma instabilities  
( experimental and numerical )

### **2.) Hot Anode Thruster ( HAT )**

- Reduction of the anode losses

### **3.) Cylindrical Thruster ( ZT-IRS )**

- Thrust measurements will hopefully resulting in

**higher  $c_e$  !**



## **MMW-Thrusters**

**MMW thruster have to be cooled actively (at least partly).**

**Cathode heat loads could be solved by geometrical configuration.**

**How to address these issues:**

- 1.) Measure heat loads in cooled devices and surface temperatures.**
- 2.) Establish thermal models ( numerical ).**
- 3.) Numerical variation of geometries and configurations.**
- 4.) Validate with new device.**



## **Facility requirements**

- 1.) Vacuum:**
  - for selffield MPD better 1 mbar**
  - for applied field MPD better  $10^{-3}$  mbar**
- 2.) Thrust balances for MMW-Thrusters are difficult to realize.**